



Model Number

PMI960-F110-IU-V1

Features

- Analog output 0 V ... 10 V/4 mA ... 20 mA
- Measuring range 0 ... 960 mm

Technical data General specifications Switching element function Object distance Measurement range Nominal ratings Operating voltage U_B Reverse polarity protected Linearity error Repeat accuracy Resolution Temperature drift No-load supply current I₀ Operating voltage display Analog output Output type Load resistor Short-circuit protection Ambient conditions

Ambient temperature Mechanical specifications Connection type Housing material

Housing length L Protection degree Note

analog, current or voltage output max. 6 mm 0 ... 960 mm

18 ... 30 V reverse polarity protected ± 0.9 mm ± 0.4 mm 960 um ± 0.9 mm (-25 °C ... 70 °C) ≤ 70 mA LED green

1 current output: 4 ... 20 mA 1 voltage output: 0 ... 10 V current output: \leq 400 Ω voltage output: \geq 1000 Ω voltage output: pulsing

-25 ... 70 °C (-13 ... 158 °F)

M12 connector PA 6 / AL 1000 mm IP65 The data relating to accuracy only apply to a distance to the object to be detected of 1 ... 6 mm. The path measurement system must be secured at 20 cm intervals to prevent mechanical load.

Standard conformity

EN 60947-5-2:2007 IEC 60947-5-2:2007

Approvals and certificates

Compliance with standards and

UL approval CCC approval

Standards

directives

cULus Listed, General Purpose, Class 2 Power Source Products with a maximum operating voltage of ≤36 V do not bear a CCC marking because they do not require approval.

Dimensions

۲ O 41 ± 0.15 10V<u>/2</u>0mA 0V/4m/ **Electrical Connection** IU 1 (BN) + UB (BK) 4-20 mA 0-10 V 3(BL - UB Core colours in accordance with EN 60947-5-2. **Pinout** Wire colors in accordance with EN 60947-5-2 ΒN 1 2 WH 3 ΒU 4 ΒK Instruction manual · Security advice This product must not be used in applications, where safety of persons depend on the correct device function. **STOF** This product is not a safety device according to EC machinery directive.

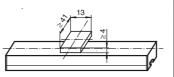
Sensor Properties

The inductive positioning system F110 provides both, a current and voltage signal at the outputs, which is proportional to the position of the attenuating element. Output signals: 4 mA ... 20 mA and 0 V ... 10 V

· Attenuating element

2

The inductive position encoding system F110 is optimally adjusted to the geometry of the attenuating elements we offer (see accessories, below).



Accessories

BT-F110-G

Damping element for F110 housing sensors; front screw holes

BT-F110-W

8 ± 0.15

30.5

Damping element for F110 housing sensors; lateral screw holes

V1-G-2M-PVC Cable socket, M12, 4-pin, PVC cable

V1-W-2M-PVC Cable socket, M12, 4-pin, PVC cable

MH-F110

Mounting bracket for mounting F110 series sensors

Subject to reasonable modifications due to technical advances

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0 ∏ Not

When using your own attenuating elements, you must ensure that the active surface of the attenuating element has a width of exactly 13 mm and overlaps the entire sensor width (41 mm). A different width has a direct impact on the achie-

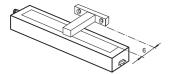
vable resolution and accuracy of the system.

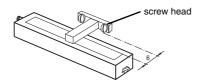
Spacing between sensor and attenuating element is from 0 ... 6 mm. Sensing accuracy is guaranteed between 1 ... 6 mm..

Installation and operation

Notes on installation

- A flush installation is possible.
- Fixation and installation of the positioning system F110 is carried out by the use of t-slides. This provides a flexible adaptation to the field situation.
- The distance between the measuring field (bordered area at the front of the sensor) and the fixing base or fixing element of the attenuating element must at least be 6 mm.

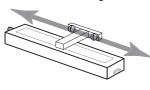


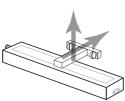


Notes on operation

The sensor accuracy can be guaranteed, when the spacing between attenuating element and sensor is within an interval of 1 ... 6 mm. When the attenuating element leaves the measurement range (figures below): - the last valid value is maintained at the voltage output until the attenuating element re-enters the valid range.

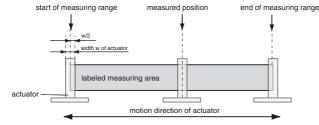
- the last valid value is maintained at the current output for 0.5 seconds. Afterwards, the output changes to a fault current of 3.6 mA until the attenuating element re-enters the valid range.





· Definition of measuring range / of measured position

The measured attenuating elements (actuators) position refers to half its width (middle of the actuator). The measuring range starts and ends when the attenuating element overlaps the labeled measuring area on the sensor at transversal motion (see left figure above).



Accessories

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Attenuating elements



Angled cables:

Straight cables:





V1-G-2M-PVC (4 wire) V1-W-2M-PVC (4 wire) Mounting brackets MH-F110



