Model Number

AVS58-0*

Features

- **Industrial standard housing Ø58 mm**
- **16 Bit singleturn**
- **Data transfer up to 2 MBaud**
- **Optically isolated RS 422 interface**
- **Servo or clamping flange**
- **Zero-set function**

Description

This singleturn absolute encoder with modern fast technology transmits a position value corresponding to the shaft setting via the SSI interface (Synchronous Serial Interface). The resolution of the AVS58 is maximum 65536 steps per revolution.

The devices of the ASM58 series are equipped with a microcontroller.

The control module sends a clock bundle to the absolute encoder to obtain the position data. The rotary encoder then sends the position data synchronous to the cycles of the control module.

It is possible to select the following items with function inputs

- the counting direction and
- the zero-set function (preset value)

This singleturn absolute encoder is available either in clamp flange design with a shaft diameter of 10 mm x 20 mm or in a servo flange design with a shaft diameter of 6 mm x 10 mm. The electrical connection is made by a 12-pin round plug connector. It is also possible to obtain a version with a 1 m cable connector.

Technical data

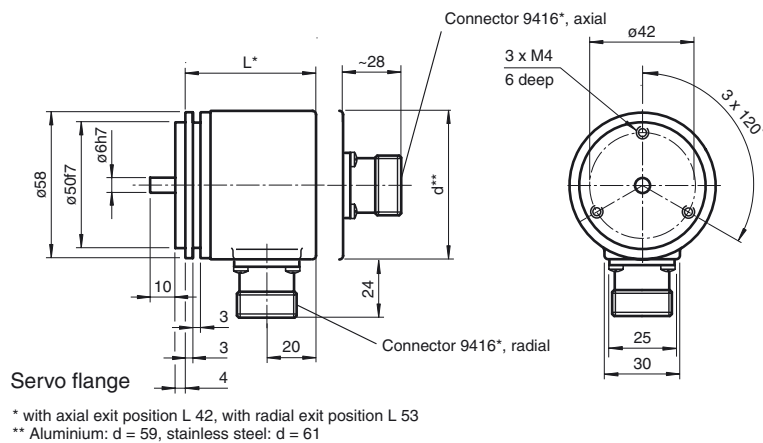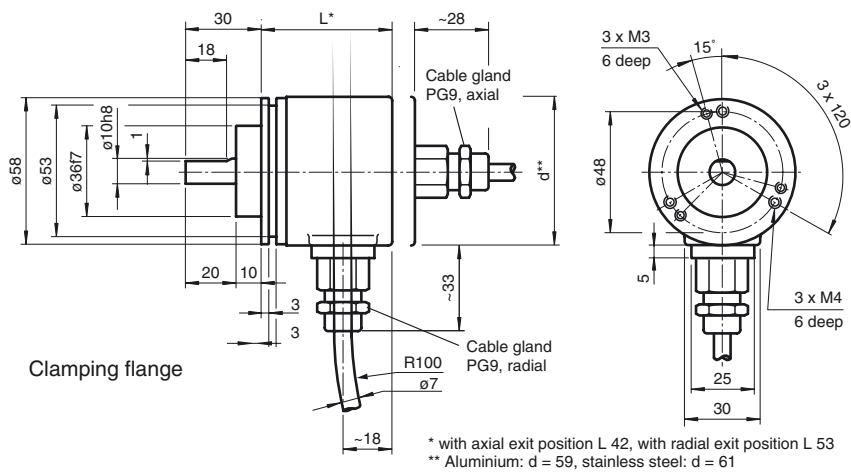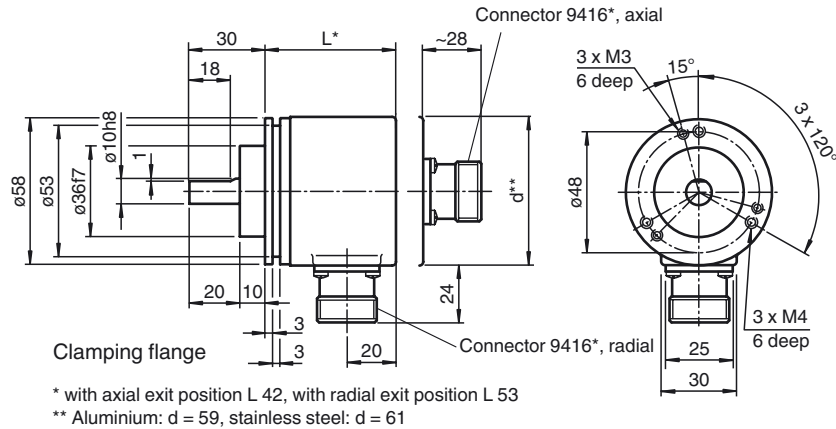| Functional safety related parameters	
$MTTF_d$	170 a
Mission Time (T_M)	20 a
L_{10h}	1.9 E+11 at 6000 rpm and 20/40 N axial/radial shaft load
Diagnostic Coverage (DC)	0 %
Electrical specifications	
Operating voltage U_B	10 ... 30 V DC
No-load supply current I_0	max. 180 mA
Linearity	± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit
Output code	Gray code, binary code
Code course (counting direction)	cw descending (clockwise rotation, code course descending)
Interface	
Interface type	SSI
Monoflop time	20 ± 10 µs
Resolution	
Single turn	up to 16 Bit
Overall resolution	up to 16 Bit
Transfer rate	0.1 ... 2 MBit/s
Voltage drop	U_B - 2.5 V
Standard conformity	RS 422
Input 1	
Input type	Selection of counting direction (V/R)
Signal voltage	
High	10 ... 30 V
Low	0 ... 2 V
Input current	< 6 mA
Signal duration	≥ 10 ms
Switch-on delay	< 0.001 ms
Input 2	
Input type	zero-set (PRESET 1)
Signal voltage	
High	10 ... 30 V
Low	0 ... 2 V
Input current	< 6 mA
Signal duration	≥ 10 ms
Switch-on delay	< 100 ms
Connection	
Connector	type 9416, 12-pin, type 9416L, 12-pin
Cable	Ø7 mm, 6 x 2 x 0.14 mm², 1 m
Standard conformity	
Protection degree	DIN EN 60529, IP65
Climatic testing	DIN EN 60068-2-3, no moisture condensation
Emitted interference	EN 61000-6-4:2007
Noise immunity	EN 61000-6-2:2005
Shock resistance	DIN EN 60068-2-27, 100 g, 3 ms
Vibration resistance	DIN EN 60068-2-6, 10 g, 10 ... 2000 Hz
Ambient conditions	
Operating temperature	-40 ... 85 °C (-40 ... 185 °F)
Storage temperature	-40 ... 85 °C (-40 ... 185 °F)
Mechanical specifications	
Material	
Combination 1	housing: powder coated aluminium flange: aluminium shaft: stainless steel
Combination 2 (Inox)	housing: stainless steel flange: stainless steel shaft: stainless steel
Mass	approx. 460 g (combination 1) approx. 800 g (combination 2)
Rotational speed	max. 12000 min⁻¹
Moment of inertia	50 gcm²
Starting torque	< 5 Ncm
Shaft load	
Axial	40 N
Radial	110 N

Approvals and certificates	
UL approval	cULus Listed, General Purpose, Class 2 Power Source

Dimensions

Clamping flange

Connector 9416*, axial
Connector 9416*, radial

3 x M3 6 deep
3 x 120°
3 x M4 6 deep

* with axial exit position L 42, with radial exit position L 53
** Aluminium: d = 59, stainless steel: d = 61

Clamping flange

Cable gland PG9, axial
Cable gland PG9, radial

3 x M3 6 deep
3 x 120°
3 x M4 6 deep

R100
ø7

* with axial exit position L 42, with radial exit position L 53
** Aluminium: d = 59, stainless steel: d = 61

Servo flange

Connector 9416*, axial
Connector 9416*, radial

3 x M4 6 deep
3 x 120°
ø42

* with axial exit position L 42, with radial exit position L 53
** Aluminium: d = 59, stainless steel: d = 61

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Servo flange

* with axial exit position L 42, with radial exit position L 53
** Aluminium: d = 59, stainless steel: d = 61

Accessories

9203

9213
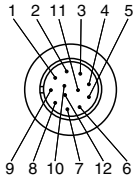Mounting bracket, spring-loaded for clamping flange
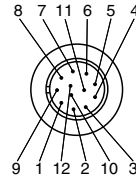
9416

9310-3
Synchro clamping element

9300
Mounting bracket for servo flange

Electrical connection

Signal	Cable Ø7 mm, 12-core	Connector 9416, 12-pin	Connector 9416L, 12-pin	Explanation
GND (encoder)	White	1	1	Power supply
U_b (encoder)	Brown	2	8	Power supply
Clock (+)	Green	3	3	Positive cycle line
Clock (-)	Yellow	4	11	Negative cycle line
Data (+)	Grey	5	2	Positive transmission data
Data (-)	Pink	6	10	Negative transmission data
Reserved	Blue	7	12	Not wired, reserved
V/R	Red	8	5	Input for selection of counting direction
PRESET 1	Black	9	9	zero-setting input
Reserved	Violet	10	4	Not wired, reserved
Reserved	Grey/Pink	11	6	Not wired, reserved
Reserved	Red/Blue	12	7	Not wired, reserved

1 2 11 3 4 5
9 8 10 7 12 6

8 7 11 6 5 4
9 1 12 2 10 3

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Description

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value.

Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

SSI signal course Standard

$D_1, ..., D_n$:	Position data		$T = 1/f$:	Duration of period of clock signal $\leq$ 1 MHz
S:	Special bit		T_m:	Monoflop time 10 μs ... 30 μs
MSB:	Most significant bit		T_p:	Clock pause $\geq$ monoflop time ($T_p \geq T_m$)
LSB:	Least significant bit			
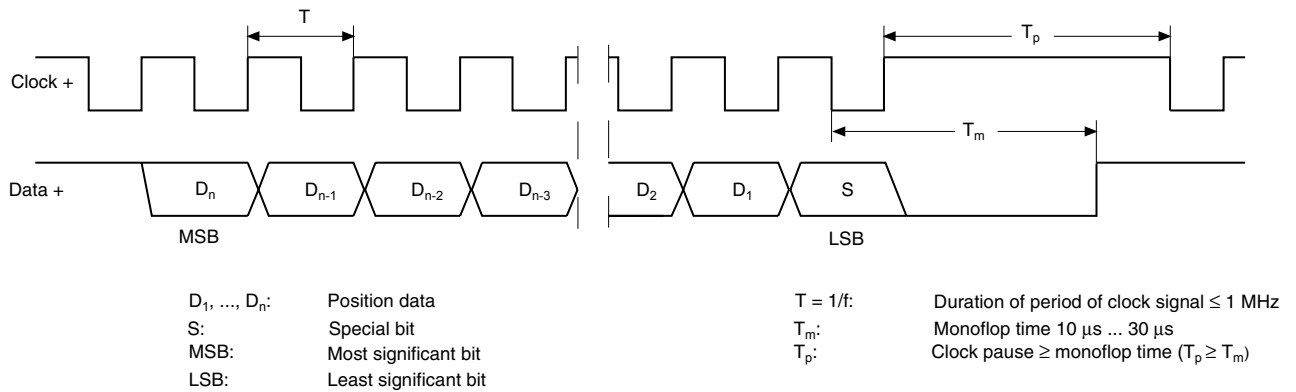
SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data (D_n) and special bit (S)) is stored in the encoder is introduced.
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time T_m has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T_p has expired.
- After the clock sequence is complete, the monoflop time T_m is triggered with the last falling pulse edge.
- The monoflop time T_m determines the lowest transmission frequency.

SSI output format ring slide operation (multiple transmission)

- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, 25 bits are transferred per data word in standard format.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first transmission, the 26th pulse controls data repetition. If the 26th pulse follows after an amount of time greater than the monoflop time T_m, a new current data word will be transmitted with the following pulses.

If the pulse line is exchanged, the data word is generated offset.
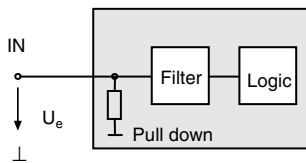Ring slide operation is possible up to max. 13 bits.

Block diagram

Rotary encoder   Interface electronics
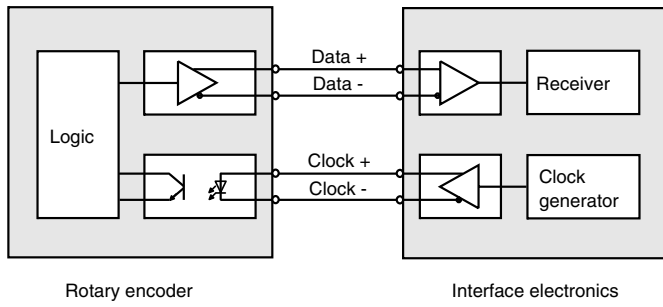
Line length

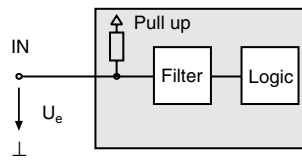| Line length in m	Baudrate in kHz
< 50	< 400
< 100	< 300
< 200	< 200
< 400	< 100

Inputs

The selection of the counting direction input (V/R) is activated with 0-level. The zero-set input (PRESET 1) is activated with 1-level.

zero-set input (PRESET 1)

Input for selection of counting direction (V/R)

Accessories

For type	Accessories	Name/defining feature	Order code
AVS58*-011	Couplings	D1: Ø10 mm, D2: Ø10 mm	9401
		D1: Ø10 mm, D2: Ø10 mm	9404
		D1: Ø10 mm, D2: Ø10 mm	9409
		D1: Ø10 mm, D2: Ø10 mm	KW
	Measurement wheels with circumference of 500 mm	Plastic	9101, 10
		Pimpled rubber	9102, 10
		Knurled aluminium	9103, 10
		Knurled plastic	9112, 10
	Measurement wheels with circumference of 200 mm	Plastic	9108, 10
		Pimpled rubber	9109, 10
		Knurled aluminium	9110, 10
		Knurled plastic	9113, 10
	Mounting aids	Mounting bracket	9203
		Mounting bracket	9213
AVS58*-032	Couplings	D1: Ø6 mm, D2: Ø6 mm	9401
		D1: Ø6 mm, D2: Ø6 mm	9402
		D1: Ø6 mm, D2: Ø6 mm	9404
		D1: Ø6 mm, D2: Ø6 mm	9409
		D1: Ø6 mm, D2: Ø6 mm	KW
	Mounting aids	Mounting bracket and set	9300 and 9311-3
		Eccentric clamping elements	9310-3
All	Connectors	Cable socket	9416
		Cable socket	9416L

For additional information on the accessories, please see the "Accessories" section.

Order code

A V S 5 8 — ☐ ☐ ☐ ☐ ☐ 0 N — 0 0 ☐ ☐

Number of bits singleturn
12 4096 (standard)
13 8192
16 65536

Output code
B Binary
G Gray

Exit position
A Axial
R Radial

Connection type
K1 Cable Ø7 mm, 6 x 2 x 0.14 mm², 1 m
AA Plug connector type 9416, 12-pin
AB Plug connector type 9416L, 12-pin

Shaft dimension/flange version
011 Shaft Ø10 mm x 20 mm with clamping flange
032 Shaft Ø6 mm x 10 mm with servo flange

Housing material
N Aluminium, powder coated
I Inox*

Principle of operation
S Singleturn

Shaft version
V Solid shaft

Data format
A SSI (Synchronous Serial Interface)

*Housing material I only available with axial exit position.